MICROCHIP

# AN540

# Implementing IIR Digital Filters

*Author:* *Amar Palacherla*
*Microchip Technology Inc.*

## INTRODUCTION

This application note describes the implementation of various digital filters using the PIC17C42, the first member of Microchip's 2nd generation of 8-bit microcontrollers. The PIC17C42 is a very high speed 8-bit microcontroller with an instruction cycle time of 250 ns (@ 16 MHz input clock). Even though the PIC17C42 is an 8-bit device, it's high speed and efficient instruction set allows implementation of digital filters for practical applications. Traditionally digital filters have been implemented using expensive Digital Signal Processors (DSPs). In a system the DSP is normally a slave processor being controlled by either an 8-bit or 16-bit microcontroller. Where sampling rates are not high (especially in mechanical control systems), a single chip solution is possible using the PIC17C42.

This application note provides a few examples of implementing digital filters. Example code for 2nd order Infinite Impulse Response (IIR) filters is given. The following type of filters are implemented:

- Low Pass
- High Pass
- Band Pass
- Band Stop (notch) filter

This application note does not explain how to design a filter. Filter design theory is well established and is beyond the scope of this application note. It is assumed that a filter is designed according to the desired specifications. The desired digital filters may be designed using either standard techniques or using commonly available digital filter design software packages.

Finite Impulse Response (FIR) filters have many advantages over IIR filters, but are much more resource intensive (both in terms of execution time and RAM). On the other hand, IIR filters are quite attractive for implementing with the PIC17C42 resources. Especially where phase information is not so important, IIR filters are a good choice (FIR filters have a linear phase response). Of the various forms used for realizing digital filters (like, Direct form, Direct II form, Cascade form, Parallel, Lattice structure, etc.) the Direct II form is used in this application note. It is easy to understand and simple macros can be built using these structures.

## THEORY OF OPERATION

Digital filters in most cases assume the following form of relationship between the output and input sequences.

$$y(n) = \sum_{i=o}^{M} a_i y(n-i) + \sum_{j=o}^{N} b_j x(n-j)$$

The above equation basically states that the present output is a weighted sum of the past inputs and past outputs. In case of FIR filters, the weighted constants $ai = 0$ and in case of IIR filters, at least one of the ai constants is non zero. In case of IIR, the above formula may be rewritten in terms of $Z$ transform as:

$$H(z) = \frac{Y(z)}{X(z)} = \frac{\sum_{k=o}^{M} b_k Z^{-k}}{1 + \sum_{k=1}^{N} a_k Z^{-k}}$$

The above equation can further be rewritten in difference equation format as follows:

$$y(n) = \sum_{i=1}^{M} a_i y(n-i) + \sum_{j=o}^{N} b_j x(n-j)$$

Realization of the above equation is called the Direct Form II structure. For example, in case of a second order structure, $M=N=2$, gives the following difference equations:

**EQUATION 1:**

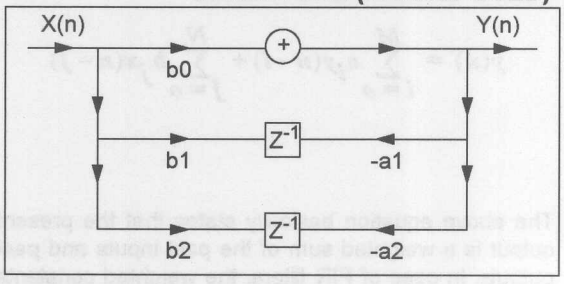
$$d(n)= x(n) + a_1 d(n-1) + a_2 d(n-2)$$

**EQUATION 2:**

$$y(n)= b_0 d(n) + b_1 d(n-1) + b_2 (d(n-2))$$

The above difference equations may be represented as shown in Figure 1.

**FIGURE 1: 2ND ORDER DIRECT FORM II STRUCTURE (TRANSPOSED)**




The structure as shown in Figure 1 may be cascaded to attain a higher order filter. For example, if two stages are cascaded together, a 4th Order IIR Filter is obtained. This way, the output of the 1st stage becomes the input to the second stage. Multiple order filters are thus implemented by cascading a 2nd order filter structure as shown in Figure 1.

## IMPLEMENTATION

A 4th order IIR Filter is implemented by cascading two of the structures shown in Figure 1. The output $Y$ (output of each filter stage) is computed by direct implementation of Equation 1 and Equation 2. Since each stage is similar algorithmically, it is implemented as a macro using Microchip's, Assembler/Linker for PIC17C42. This Macro (labelled `BIQUAD`) is called twice for implementing a 4th order filter. The output of the 1st stage is directly fed to the input of the second stage without any scaling.

Scaling may be required depending on the particular application. The user can modify the code very easily without any penalty on speed. Also, saturation arithmetic is not used. Overflows can be avoided by limiting the input sequence amplitude. All numbers are assumed to be 16 bits in Q15 format (15 decimal points, MSb is sign bit). Thus the user must scale and sign extend the input sequence accordingly. For example, if the input is from a 12-bit A/D converter, the user must sign extend the 12-bit input if bit 11 is a one.

The `BIQUAD` macro is a generic macro and can be used for all IIR filters whether it is Low Pass, High Pass, Band Pass or Band Stop. A general purpose 16x16 multiplier routine is also provided. This routine is implemented as a straight line code for speed considerations.

The 4th order IIR filter implemented is a Low Pass Filter with the specifications shown in Table 1.

**TABLE 1: FILTER CONSTANTS**

| | BAND1 | BAND2 |
|---|---|---|
| Lower Band Edge | 0.0 | 600 Hz |
| Upper Band Edge | 500 Hz | 1 kHz |
| Nominal Gain | 1.0 | 0.0 |
| Nominal Ripple | 0.01 | 0.05 |
| Maximum Ripple | 0.00906 | 0.04601 |
| Ripple in dB | 0.07830 | -26.75 |
| Sampling Frequency = 2 kHz | | |

The Low Pass Filter is designed using a digital filter design package (DFDP™ by Atlanta Signal Processors Inc.). The filter package produces filter constants of the structure shown in Table 1. Table 2 shows the filter co-efficients that are obtained for the above Low Pass filter specification.

**TABLE 2: FILTER CO-EFFICIENTS**

| Stage | Co-efficients | | | | |
|---|---|---|---|---|---|
| | a1 | a2 | b0 | b1 | b2 |
| 1 | -0.133331 | 0.167145 | 0.285431 | 0.462921 | 0.285431 |
| 2 | 0.147827 | 0.765900 | 0.698273 | 0.499908 | 0.698273 |

The above filter co-efficients (5 per stage) are quantized to Q15 format (i.e they are multiplied by 32768) and saved in program memory (starting at label `_coeff_lpass`). The constants for both the stages are read into data memory using `TLRD` and `TABLRD` instructions in the Initialization Routine (labelled `initFilter`). The user may read the coefficients of only one stage at a time and save some RAM at the expense of speed.

The sample 4th order Low Pass IIR Filter is tested by analyzing the impulse response of the filter. An impulse signal is fed as input to the filter. This is simulated by forcing the input to the filter by a large quantity (say 7F00h) on the first input sample, and the all zeros from the 2nd sample onwards. The output sequence is the filter's impulse response and is captured into the PICMASTER's (Microchip's Universal In-Circuit Emulator) real-time trace buffer. This captured data from PICMASTER is saved to file and analyzed. Analysis was done using MathCad™ for Windows® and a DSP Analysis program from Burr-Brown (DSPLAY™). The Fourier Transform of this impulse response of the filter should display the filter's frequency response, in this case being a Low Pass type. The plots of the impulse response and the frequency response are shown in Figure 2, Figure 3 and Figure 4.

MathCad is a trademark of MathSoft, Inc.
DSPLAY is a trademark of Burr-Brown
DFDP is a trademark of Atlanta Signal Processing Inc.
Windows is a registered trademark of Microsoft Corporation.

**FIGURE 2: IMPULSE RESPONSE CAPTURED FROM PICMASTER**

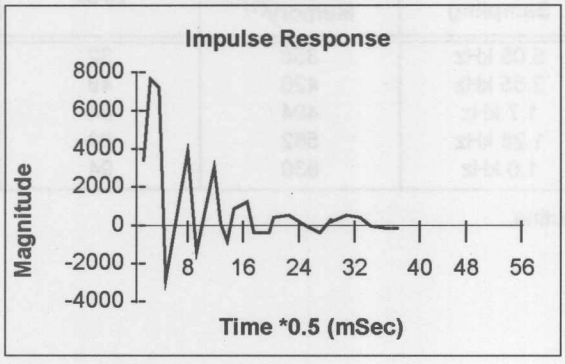
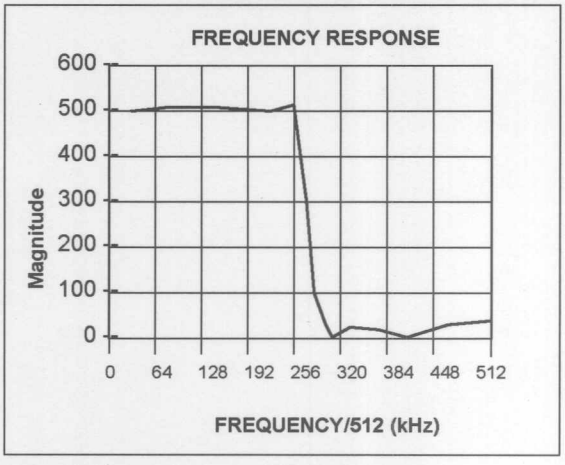



**FIGURE 3: SPECTRUM COMPUTED FROM IMPULSE RESPONSE**




## PERFORMANCE

The resource requirements for filter implementations using a PIC17C42 is given in Table 3. These numbers can be used to determine whether a higher order filter can be executed in real-time. The same information may be used to determine the highest sampling rate possible.

## FILTER APPLICATIONS

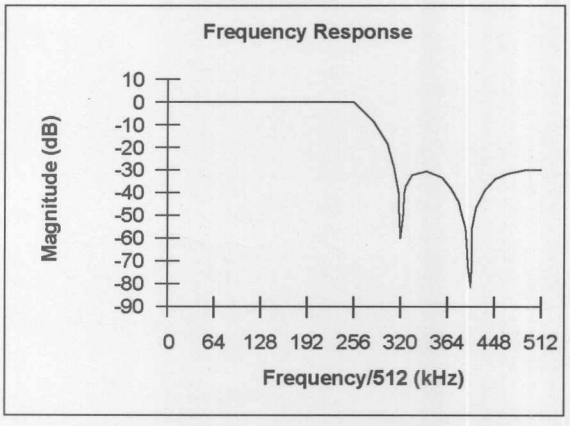
Digital filters find applications in many areas especially those involving processing of real world signals. In some applications like ABS systems in an automobile, digital filtering becomes a must. In this case elimination of noise (especially glitches and false readings of sensors) is very critical and thus becomes a requirement of digital signal processing.

**TABLE 3: RESOURCE REQUIREMENTS**

| | |
|---|---|
| Timing (Cycles)(1) | #of Filter Stages*775 + 16 |
| Program Memory (locations)(1) | #of Filter Stages*68 + 290 |
| RAM (File Registers) | #of Filter Stages*16 + 16 |

Note 1: The above numbers do not include the initialization routine.

**FIGURE 4: LOG MAGNITUDE SPECTRUM OF IMPULSE RESPONSE**




Digital filters are also needed in Process Control where notch filters and low pass filters are desired because the signals from sensors are transmitted over long lines, especially in a very noisy environment. In these cases, typically a notch filter (centering 50 Hz or 60 Hz) is used. In cases of eliminating background noise, a band stop filter (e.g., 40 Hz to 120 Hz) is used. The sample code given in this application note can be used to design a feedback control system's digital compensator. For example, a typical DC Motor's digital compensator (like a dead-beat compensator) is of second order and has the same filter structure that is implemented in this application note.

**TABLE 4: RESOURCE REQUIREMENTS**

| Filter Order | Cycles | Real Time (@16 MHz) | Maximum Sampling | Program Memory(1) | RAM |
|---|---|---|---|---|---|
| 2 | 791 | 197.75 µs | 5.05 kHz | 358 | 32 |
| 4 | 1566 | 391.5 µs | 2.55 kHz | 426 | 48 |
| 6 | 2341 | 585.25 µs | 1.7 kHz | 494 | 64 |
| 8 | 3116 | 779.0 µs | 1.28 kHz | 562 | 80 |
| 10 | 3891 | 972.75 µs | 1.0 kHz | 630 | 94 |

Note 1: The above numbers do not include the initialization routine.

Please check the Microchip BBS for the latest version of the source code. Microchip's Worldwide Web Address: www.microchip.com; Bulletin Board Support: MCHIPBBS using CompuServe® (CompuServe membership not required).

## APPENDIX A: IIR.LS0T

```
MPASM 01.40 Released              IIR.ASM   1-16-1997  14:48:37         PAGE  1


LOC  OBJECT CODE     LINE SOURCE TEXT
  VALUE

                     00001         TITLE   "Digital IIR Filter Using PIC17C42"
                     00002
                     00003         LIST    P=17C42, columns=120,WRAP, R = DEC
                     00004
                     00005                 #include <p17c42.inc>
                     00001         LIST
                     00002 ;P17C42.INC Standard Header File, Version 1.03 Microchip Technology, Inc.
                     00264         LIST
                     00006
                     00007         #define true    1
                     00008         #define false   0
                     00009         #define TRUE    1
                     00010         #define FALSE   0
                     00011
                     00012         #define LSB     0
                     00013         #define MSB     7
                     00014
00000001             00015 _INC    equ     1
00000000             00016 _NO_INC equ     0
00000000             00017 _LOW    equ     0
00000001             00018 _HIGH   equ     1
                     00019
                     00020                 #include <17c42.mac>
                     00945         LIST
                     00021
                     00022                 #include <17c42iir.mac>
                     00001         LIST
                     00002 ;*****************************************************************
                     00003 ;                       PIC17C42 MACRO
                     00004 ;
                     00005 ;Macro For A Bi-Quad IIR Filter
                     00006 ;       2nd order Direct Form (Transposed) Type
                     00007 ;
                     00008 ; Filter co-efficients B0 & B2 are assumed equal
                     00009 ;
                     00010 ; The difference equations for each cascade section is given by :
                     00011 ;         Y(n) = B0*D(n) + B1*D(n-1) + B2*D(n-2)
                     00012 ;         D(n) = X(n) - A1*D(n-1) -  A2*D(n-2)
                     00013 ;    where X(n) = input sample, Y(n) = output of filter
                     00014 ;    and A1, A2, B0, B1, B2 are the Filter Co-efficients
                     00015 ;
                     00016 ;  The above difference equations are only for 1 section of a
                     00017 ; 2nd order Direct_Form II Filter structure (IIR)
                     00018 ;
                     00019 ;   NOTE :
                     00020 ;       It is possible to design the above structures
                     00021 ;       such that the co-efficients B0 = B2. If this is the
                     00022 ;       case,
                     00023 ;       Y(n) = B0*[D(n) + D(n-2)] = B2*[D(n) + D(n-2)]
                     00024 ;       This way, one multiplication can be avoided
                     00025 ;
                     00026 ;  If a 4th order filter is to be implemented, the output of
                     00027 ; the 1st structure should be input to the 2nd cascade section
                     00028 ;
```

```
00029 ;       Timing (WORST CASE) :
00030 ;              59+4*179 = 775 Cycles
00031 ;              (194 uS @ 16 Mhz)
00032 ;              Program Memory  :
00033 ;              63 locations
00034 ;
00035 ;*****************************************************************
00036 ;       The sample filters are designed so that B0=B2
00037 ;       This saves 1 multiplication
00038 ;
00000001 00039 B0_EQUALS_B2    equ     TRUE
00040 ;
00041 ;*****************************************************************
00042 ;  Parameters to BIQUAD Macro :
00043 ;              Filter Constants A1, A2, B0, B1, B2
00044 ;              & D(n), D(n-1), D(n-2), filter stage #
00045 ;
00046 BIQUAD  MACRO   Ax1,Ax2,Bx0,Bx1,Dn,Dn_1,Dn_2,stage
00047
00048 ;
00049 ; Compute Ax2*D(n-2)
00050 ;
00051  MOVFP16  Dn_2,AARG      ; D(n-2) = multiplier
00052  MOVFP16  Ax2,BARG       ; A2 = multiplicand
00053         call    DblMult  ; (ACCd,ACCc) = A2*D(n-2)
00054 ;
00055 ; Add product to output of 1st section
00056 ; Save result in 32 bit Accumulator
00057 ;
00058         ADD32    DPX,ACC
00059 ;
00060 ;  Compute A1*D(n-1)
00061 ;
00062  MOVFP16  Dn_1,AARG      ; AARG = D(n-2) = multiplier
00063  MOVFP16  Ax1,BARG       ; BARG = A2 = multiplicand
00064         call    DblMult          ; (ACCd,ACCc) = A1*D(n-1)
00065 ;
00066 ; Compute A1*D(n-1) + A2*D(n-2) + output of previous section
00067 ;       multiplications already done, so simply perform a 32 bit add
00068 ;       of previously obtained multiplication results
00069 ;
00070   ADD32   DPX,ACC ; ACC = A1*D(n-1) + A2*D(n-2) + (output of 1st section)
00071 ;
00072 ;
00073 ; save the upper 16 bits  of D(n) from the 32 bit accumulator
00074 ; left shift the result by 1, to adjust the decimal point after
00075 ; a Q15*Q15 multiplication
00076 ;
00077         rlcf     ACC+B1,w
00078         rlcf     ACC+B2,w
00079         movwf     Dn
00080         rlcf     ACC+B3,w        ; decimal adjust ( mult by 2)
00081         movwf     Dn+B1
00082 ;
00083 ; Compute B2 * [D(n) + D(n-2)]
00084 ;
00085         #if B0_EQUALS_B2
00086
00087         ADD16ACC   Dn_2,Dn,AARG    ; AARG = Dn + D(n-2) = multiplier
00088  MOVFP16    Bx0,BARG        ; BARG = A2 = multiplicand
00089         call       DblMult          ; (ACCd,ACCc) = B2*[D(n)+D(n-2)]
00090  MOVPF32    DPX,ACC
00091
00092         #else
00093
00094  MOVFP16    Bx0,BARG
```

```
00095  MOVFP16    Dn,AARG
00096          call       DblMult          ; B0*D(n)
00097  MOVPF32    DPX,ACC
00098
00099  MOVFP16    Bx2,BARG
00100  MOVFP16    Dn_2,AARG
00101          call       DblMult          ; B2*D(n-2)
00102          ADD32      DPX,ACC
00103
00104          #endif
00105 ;
00106 ; Shift down D(n-1) to D(n-2) after D(n-2) usage is no longer required.
00107 ; This way in the next iteration D(n-2) is equal to the present D(n-1)
00108 ;
00109          movfp      Dn_1,AARG+B0
00110          movpf      AARG+B0,Dn_2     ; Shift down D(n-1)
00111          movfp      Dn_1+B1,AARG+B1
00112          movpf      AARG+B1,Dn_2+B1  ; AARG = D(n-1) = multiplier
00113
00114  MOVFP16   Bx1,BARG          ; BARG = B1 = multiplicand
00115
00116          call       DblMult          ; (ACCd,ACCc) = B1*D(n-1)
00117 ;
00118 ; Compute Output Y = B1*D(n-1) + B2*D(n-2) + B0*D(n)
00119 ;                 = B1*D(n-1) + B0*[D(n) + D(n-2)]
00120 ; Since all multiplications are already done, simply perform a
00121 ; 32 bit addition
00122 ;
00123          ADD32      DPX,ACC ; ACC = B1*D(n-1) + B2*D(n-2) + B0*D(n)
00124 ;
00125 ; Shift down D(n) to D(n-1) so that in the next iteration, the new
00126 ; D(n-1) is the present D(n)
00127 ;
00128  MOV16     Dn,Dn_1 ; Shift down D(n) to D(n-1)
00129 ;
00130          ENDM
00131
00132          LIST
00023 ;
00024 ;*****************************************************************
00025 ;                Second Order Direct Form IIR Filter
00026 ;
00027 ;
00028 ; In the code given below, a 4th order IIR Elliptic Lowpass Filter
00029 ; is implemented. Other order filters may be implemented by
00030 ; taking the following example code as a basis.
00031 ;
00032 ;
00033 ;       Program:          IIR.ASM
00034 ;       Revision Date:
00035 ;                         1-13-97      Compatibility with MPASMWIN 1.40
00036 ;
00037 ;*****************************************************************
00038 ;
00039 ;       The specifications of the filter are :
00040 ;
00041 ;       Sampling Frequency = 2.0 Khz
00042 ;
00043 ;       Filter Type = 4th Order Elliptic Lowpass Filter
00044 ;
00045 ;                                 Band1          Band2
00046 ;       Lower Band Edge  0.0                600 Hz
00047 ;       Upper Band Edge           500 Hz          1 Khz
00048 ;       Nominal Gain              1.0       0.0
00049 ;       Nominal Ripple    0.01      0.05
00050 ;Maximum Ripple    0.00906   0.04601
```

```
00051 ;       Ripple in dB     0.07830         -26.75
00052 ;
00053 ;  The Filter Co-efficients for the above specifications
00054 ; of the filter are computed as follows :
00055 ;
00056 ;      1st Section :
00057 ;                          A11 = -0.133331
00058 ;                          A12 = 0.167145
00059 ;                          B10 = 0.285431
00060 ;                          B11 = 0.462921
00061 ;                          B12 = 0.285431
00062 ;      2nd Section
00063 ;                          A21 = 0.147827
00064 ;                          A22 = 0.765900
00065 ;                          B20 = 0.698273
00066 ;                          B21 = 0.499908
00067 ;                          B22 = 0.698273
00068 ;
00069 ;
00070 ;      Performance (WORST Case):
00071 ;
00072 ;                          Cycles    = #of Filter Stages*775 + 16
00073 ;                                    = 2*775+16 = 1566 Cycles
00074 ;                                      ( 391 uSec)
00075 ;                                  per each sample. Initialization
00076 ;                                  time after reset is not counted
00077 ;                                  Timing measured with B0_EQUALS_B2
00078 ;                                  set to TRUE (see BIQUAD Macro for
00079 ;                                  explanation)
00080 ;
00081 ;                    Program Memory :
00082 ;                                  = 16+ # of FilterStages * (BIQUAD Memory
00083 ;                                          + filter co-efficients)
00084 ;                                          + multiplier
00085 ;                                  = 16+2*(63+5)+274 = 421 locations
00086 ;                                    (excluding initialization)
00087 ;
00088 ;                          RAM usage = 48 file registers
00089 ;                          RAM usage/each additional stage = 16 file regs
00090 ;
00091 ;
00092 ;                          This time is less than 2 Khz (500 uSec),
00093 ;                          which means real time filtering is possible
00094 ;
00095 ;*****************************************************************
00096
00097 ;*****************************************************************
00098 ;
00099 ;
00100         CBLOCK  0
00000000    00101                 BB0,BB1,BB2,BB3
00102         ENDC
00103 ;*****************************************************************
00104 ;
00105     CBLOCK  0x18
00000018    00106         DPX,DPX1,DPX2,DPX3              ; arithmetic accumulator
0000001C    00107         AARG,AARG1,BARG,BARG1           ; multiply arguments
00108     ENDC
00109 ;
00110     CBLOCK
00000020    00111             Dn1,    Dn1_Hi
00000022    00112             Dn1_1,  Dn1_1_Hi
00000024    00113             Dn1_2,  Dn1_2_Hi
00114
00000026    00115             Dn2,    Dn2_Hi
00000028    00116             Dn2_1,  Dn2_1_Hi
```

```
0000002A  00117             Dn2_2, Dn2_2_Hi
          00118       ENDC
          00119
          00120       CBLOCK
0000002C  00121             A11, A11_Hi
0000002E  00122             A12, A12_Hi
00000030  00123             B10, B10_Hi
00000032  00124             B11, B11_Hi          ; 1st Section Filter Co-efficients
00000034  00125             B12, B12_Hi
          00126
00000036  00127             A21, A21_Hi
00000038  00128             A22, A22_Hi
0000003A  00129             B20, B20_Hi
0000003C  00130             B21, B21_Hi          ; 2nd Section Filter Co-efficients
0000003E  00131             B22, B22_Hi
          00132       ENDC
          00133
          00134       CBLOCK
00000040  00135             X, X1                ; 16 bits of input stream
00000042  00136             Y, Y1                ; 16 bits of filter output
          00137
00000044  00138             ACC, ACC1, ACC2, ACC3 ; 32 bit accumulator for computations
          00139       ENDC
          00140 ;
00000002  00141 FltStage  .set  2
0000000A  00142 NumCoeff  equ   (5*FltStage)     ; 5 Co-eff per stage
          00143 ;
00000001  00144 F         equ   1
          00145 ;
00000001  00146 LPASS     .set  TRUE
00000000  00147 HPASS     .set  FALSE
00000000  00148 BPASS     .set  FALSE            ; select the desired filter type
00000000  00149 BSTOP     .set  FALSE
          00150 ;
00000001  00151 SIGNED    equ   TRUE             ; Set This To 'TRUE' for signed
          00152 ;                                ; multiplication and 'FALSE' for unsigned.
          00153 ;
          00154 ;*****************************************************************
          00155 ;               Test Program For Low Pass Filter
          00156 ;*****************************************************************
          00157
0000      00158         ORG     0x0000
          00159 ;
0000      00160 start
0000 E00D 00161         call    initFilter
0001 B000 00162         movlw   0x00
0002 0140 00163         movwf   X
0003 B07F 00164         movlw   0x7f             ; set initial Xn = X(0) = 0x7f00
0004 0141 00165         movwf   X+BB1            ; test for impulse response
          00166 ;
0005      00167 NextPoint
0005 E022 00168         call    IIR_Filter
0006 A442 00169         tlwt    _LOW,Y
0007      00170 tracePoint
0007 AE43 00171         tablwt  _HIGH,0,Y+BB1
0008 0000 00172         nop
0009 2940 00173         clrf    X, F             ; set X(n) = 0 , n <> 0
000A 2941 00174         clrf    X+BB1, F         ; for simulating an Impulse
000B C005 00175         goto    NextPoint
          00176 ;
000C C00C 00177 self    goto    self
          00178 ;
          00179 ;*****************************************************************
          00180 ;
000D      00181 initFilter
          00182 ;
```

```
                00183 ;   At first read the Filter Co-efficients from Prog. Mem to Data RAM
                00184 ;
                00185         #if     LPASS
000D B0C1       00186                 movlw   LOW     _coeff_lpass
000E 010D       00187                 movwf   TBLPTRL
000F B001       00188                 movlw   HIGH    _coeff_lpass
0010 010E       00189                 movwf   TBLPTRH
                00190         #endif
                00191         #if     HPASS
                00192                 movlw   LOW     _coeff_hpass
                00193                 movwf   TBLPTRL
                00194                 movlw   HIGH    _coeff_hpass
                00195                 movwf   TBLPTRH
                00196         #endif
                00197         #if     BPASS
                00198                 movlw   LOW     _coeff_bpass
                00199                 movwf   TBLPTRL
                00200                 movlw   HIGH    _coeff_bpass
                00201                 movwf   TBLPTRH
                00202         #endif
                00203         #if     BSTOP
                00204                 movlw   LOW     _coeff_bstop
                00205                 movwf   TBLPTRL
                00206                 movlw   HIGH    _coeff_bstop
                00207                 movwf   TBLPTRH
                00208         #endif
                00209
                00210 ;
0011 B02C       00211         movlw   A11
0012 0101       00212         movwf   FSR0
0013 8404       00213         bsf     ALUSTA,FS0
0014 8D04       00214         bcf     ALUSTA,FS1              ; auto increment
                00215 ;
                00216 ; Read Filter Co-efficients from Program Memory
                00217 ;
0015 B00A       00218         movlw   NumCoeff
0016 A92C       00219         tablrd  _LOW,_INC,A11         ; garbage
0017            00220 NextCoeff
0017 A000       00221         tlrd    _LOW,INDF0
0018 AB00       00222         tablrd  _HIGH,_INC,INDF0
0019 170A       00223         decfsz  WREG, F
001A C017       00224         goto    NextCoeff
                00225 ;
                00226 ; Initialize "Dn"s to zero
                00227 ;
001B B020       00228         movlw   Dn1
001C 0101       00229         movwf   FSR0
001D B00C       00230         movlw   6*FltStage
001E            00231 NextClr
001E 2900       00232         clrf    INDF0, F
001F 170A       00233         decfsz  WREG, F
0020 C01E       00234         goto    NextClr
                00235 ;
0021 0002       00236         return
                00237 ;
                00238 ;*****************************************************************
                00239 ;                       1st Cascade Section
                00240 ;*****************************************************************
                00241 ;
0022            00242 IIR_Filter
                00243 ;
                00244 ; Compute  D(n) = X(n) + A1*D(n-1) + A2*D(n-2)
                00245 ;          Since the filter constants are computated in Q15 format,
                00246 ;          X(n) must be multiplied by 2**15 and then added to the
                00247 ;          other terms.
                00248 ;
```

```
                00249 ; Move Input to accumulator after proper scaling
                00250 ;
0022 8804       00251         bcf     ALUSTA,C
0023 1941       00252         rrcf    X+BB1, F
0024 1940       00253         rrcf    X, F
0025 290A       00254         clrf    WREG, F     ; Scale the input X
0026 190A       00255         rrcf    WREG, F
0027 0145       00256         movwf   ACC+BB1
0028 6A40       00257         movfp   X,WREG
0029 0146       00258         movwf   ACC+BB2
002A 6A41       00259         movfp   X+BB1,WREG
002B 0147       00260         movwf   ACC+BB3     ; ACC = scaled input : X*(2**15)
                00261 ;
                00262 ; 1st Biquad filter section
                00263 ;
                00264         BIQUAD  A11,A12,B10,B11,Dn1,Dn1_1,Dn1_2,1
                    M
                    M ;
                    M ; Compute Ax2*D(n-2)
                    M ;
                    M   MOVFP16 Dn1_2,AARG        ; D(n-2) = multiplier
                    M
002C 7C24           M   MOVFP   Dn1_2+B0,AARG+B0 ; move A(B0) to B(B0)
002D 7D25           M   MOVFP   Dn1_2+B1,AARG+B1 ; move A(B1) to B(B1)
                    M
                    M   MOVFP16 A12,BARG          ; A2 = multiplicand
                    M
002E 7E2E           M   MOVFP   A12+B0,BARG+B0    ; move A(B0) to B(B0)
002F 7F2F           M   MOVFP   A12+B1,BARG+B1    ; move A(B1) to B(B1)
                    M
0030 E0AF           M   call    DblMult           ; (ACCd,ACCc) = A2*D(n-2)
                    M ;
                    M ; Add product to output of 1st section
                    M ; Save result in 32 bit Accumulator
                    M ;
                    M   ADD32   DPX,ACC
                    M
0031 6A18           M   MOVFP   DPX+B0,WREG       ; get lowest byte of a into w
0032 0F44           M   ADDWF   ACC+B0, F         ; add lowest byte of b, save in b(B0)
0033 6A19           M   MOVFP   DPX+B1,WREG       ; get 2nd byte of a into w
0034 1145           M   ADDWFC  ACC+B1, F         ; add 2nd byte of b, save in b(B1)
0035 6A1A           M   MOVFP   DPX+B2,WREG       ; get 3rd byte of a into w
0036 1146           M   ADDWFC  ACC+B2, F         ; add 3rd byte of b, save in b(B2)
0037 6A1B           M   MOVFP   DPX+B3,WREG       ; get 4th byte of a into w
0038 1147           M   ADDWFC  ACC+B3, F         ; add 4th byte of b, save in b(B3)
                    M
                    M ;
                    M ;  Compute A1*D(n-1)
                    M ;
                    M   MOVFP16  Dn1_1,AARG       ; AARG = D(n-2) = multiplier
                    M
0039 7C22           M   MOVFP   Dn1_1+B0,AARG+B0  ; move A(B0) to B(B0)
003A 7D23           M   MOVFP   Dn1_1+B1,AARG+B1  ; move A(B1) to B(B1)
                    M
                    M   MOVFP16  A11,BARG         ; BARG = A2 = multiplicand
                    M
003B 7E2C           M   MOVFP   A11+B0,BARG+B0    ; move A(B0) to B(B0)
003C 7F2D           M   MOVFP   A11+B1,BARG+B1    ; move A(B1) to B(B1)
                    M
003D E0AF           M   call    DblMult           ; (ACCd,ACCc) = A1*D(n-1)
                    M ;
                    M ; Compute A1*D(n-1) + A2*D(n-2) + output of previous section
                    M ;       multiplications already done, so simply perform a 32 bit add
                    M ;       of previously obtained multiplication results
                    M ;
                    M   ADD32   DPX,ACC                 ; ACC = A1*D(n-1) + A2*D(n-2) +
```

```
                M                                       ;              (output of 1st section)
003E 6A18       M   MOVFP   DPX+B0,WREG                 ; get lowest byte of a into w
003F 0F44       M   ADDWF   ACC+B0, F                   ; add lowest byte of b, save in b(B0)
0040 6A19       M   MOVFP   DPX+B1,WREG                 ; get 2nd byte of a into w
0041 1145       M   ADDWFC  ACC+B1, F                   ; add 2nd byte of b, save in b(B1)
0042 6A1A       M   MOVFP   DPX+B2,WREG                 ; get 3rd byte of a into w
0043 1146       M   ADDWFC  ACC+B2, F                   ; add 3rd byte of b, save in b(B2)
0044 6A1B       M   MOVFP   DPX+B3,WREG                 ; get 4th byte of a into w
0045 1147       M   ADDWFC  ACC+B3, F                   ; add 4th byte of b, save in b(B3)
                M
                M ;
                M ;
                M ; save the upper 16 bits  of D(n) from the 32 bit accumulator
                M ; left shift the result by 1, to adjust the decimal point after
                M ; a Q15*Q15 multiplication
                M ;
0046 1A45       M   rlcf    ACC+B1,w
0047 1A46       M   rlcf    ACC+B2,w
0048 0120       M   movwf   Dn1
0049 1A47       M   rlcf    ACC+B3,w                    ; decimal adjust ( mult by 2)
004A 0121       M   movwf   Dn1+B1
                M ;
                M ; Compute B2 * [D(n) + D(n-2)]
                M ;
                M   #if B0_EQUALS_B2
                M
                M    ADD16ACC  Dn1_2,Dn1,AARG       ; AARG = Dn + D(n-2) = multiplier
                M
004B 6A24       M    movfp   Dn1_2+B0,WREG
004C 0E20       M    addwf   Dn1+B0,w
004D 011C       M    movwf   AARG+B0
004E 6A25       M    movfp   Dn1_2+B1,WREG
004F 1021       M    addwfc  Dn1+B1,w
0050 011D       M    movwf   AARG+B1
                M
                M    MOVFP16  B10,BARG              ; BARG = A2 = multiplicand
                M
0051 7E30       M    MOVFP   B10+B0,BARG+B0         ; move A(B0) to B(B0)
0052 7F31       M    MOVFP   B10+B1,BARG+B1         ; move A(B1) to B(B1)
                M
0053 E0AF       M    call    DblMult                ; (ACCd,ACCc) = B2*[D(n)+D(n-2)]
                M    MOVPF32  DPX,ACC
                M
0054 5844       M    MOVPF   DPX+B0,ACC+B0          ; move A(B0) to B(B0)
0055 5945       M    MOVPF   DPX+B1,ACC+B1          ; move A(B1) to B(B1)
0056 5A46       M    MOVPF   DPX+B2,ACC+B2          ; move A(B2) to B(B2)
0057 5B47       M    MOVPF   DPX+B3,ACC+B3          ; move A(B3) to B(B3)
                M
                M
                M    #else
                M
                M     MOVFP16 B10,BARG
                M     MOVFP16 Dn1,AARG
                M     call    DblMult                ; B0*D(n)
                M     MOVPF32 DPX,ACC
                M
                M     MOVFP16 Bx2,BARG
                M     MOVFP16 Dn1_2,AARG
                M     call    DblMult                ; B2*D(n-2)
                M     ADD32   DPX,ACC
                M
                M     #endif
                M ;
                M ; Shift down D(n-1) to D(n-2) after D(n-2) usage is no longer required.
                M ; This way in the next iteration D(n-2) is equal to the present D(n-1)
                M ;
```

```
0058 7C22        M    movfp    Dn1_1,AARG+B0
0059 5C24        M    movpf    AARG+B0,Dn1_2        ; Shift down D(n-1)
005A 7D23        M    movfp    Dn1_1+B1,AARG+B1
005B 5D25        M    movpf    AARG+B1,Dn1_2+B1     ; AARG = D(n-1) = multiplier
                 M
                 M    MOVFP16  B11,BARG             ; BARG = B1 = multiplicand
                 M
005C 7E32        M    MOVFP    B11+B0,BARG+B0       ; move A(B0) to B(B0)
005D 7F33        M    MOVFP    B11+B1,BARG+B1       ; move A(B1) to B(B1)
                 M
                 M
005E E0AF        M    call     DblMult              ; (ACCd,ACCc) = B1*D(n-1)
                 M ;
                 M ; Compute Output Y = B1*D(n-1) + B2*D(n-2) + B0*D(n)
                 M ;                  = B1*D(n-1) + B0*[D(n) + D(n-2)]
                 M ; Since all multiplications are already done, simply perform a
                 M ; 32 bit addition
                 M ;
                 M    ADD32    DPX,ACC ; ACC = B1*D(n-1) + B2*D(n-2) + B0*D(n)
                 M
005F 6A18        M    MOVFP    DPX+B0,WREG          ; get lowest byte of a into w
0060 0F44        M    ADDWF    ACC+B0, F            ; add lowest byte of b, save in b(B0)
0061 6A19        M    MOVFP    DPX+B1,WR            ; get 2nd byte of a into w
0062 1145        M    ADDWFC   ACC+B1, F            ; add 2nd byte of b, save in b(B1)
0063 6A1A        M    MOVFP    DPX+B2,WREG          ; get 3rd byte of a into w
0064 1146        M    ADDWFC   ACC+B2, F            ; add 3rd byte of b, save in b(B2)
0065 6A1B        M    MOVFP    DPX+B3,WREG          ; get 4th byte of a into w
0066 1147        M    ADDWFC   ACC+B3, F            ; add 4th byte of b, save in b(B3)
                 M
                 M ;
                 M ; Shift down D(n) to D(n-1) so that in the next iteration, the new
                 M ; D(n-1) is the present D(n)
                 M ;
                 M    MOV16    Dn1,Dn1_1 ; Shift down D(n) to D(n-1)
                 M
0067 6A20        M    MOVFP    Dn1+B0,WREG          ; get byte of a into w
0068 0122        M    MOVWF    Dn1_1+B0             ; move to b(B0)
0069 6A21        M    MOVFP    Dn1+B1,WREG          ; get byte of a into w
006A 0123        M    MOVWF    Dn1_1+B1             ; move to b(B1)
                 M
                 M ;
              00265 ;
              00266 ; 2nd Biquad filter section
              00267 ;
              00268    BIQUAD   A21,A22,B20,B21,Dn2,Dn2_1,Dn2_2,2
                 M
                 M ;
                 M ; Compute Ax2*D(n-2)
                 M ;
                 M    MOVFP16  Dn2_2,AARG           ; D(n-2) = multiplier
                 M
006B 7C2A        M    MOVFP    Dn2_2+B0,AARG+B0     ; move A(B0) to B(B0)
006C 7D2B        M    MOVFP    Dn2_2+B1,AARG+B1     ; move A(B1) to B(B1)
                 M
                 M    MOVFP16  A22,BARG             ; A2 = multiplicand
                 M
006D 7E38        M    MOVFP    A22+B0,BARG+B0       ; move A(B0) to B(B0)
006E 7F39        M    MOVFP    A22+B1,BARG+B1       ; move A(B1) to B(B1)
                 M
006F E0AF        M    call     DblMult              ; (ACCd,ACCc) = A2*D(n-2)
                 M ;
                 M ; Add product to output of 1st section
                 M ; Save result in 32 bit Accumulator
                 M ;
                 M    ADD32    DPX,ACC
                 M
```

```
0070 6A18        M    MOVFP   DPX+B0,WREG          ; get lowest byte of a into w
0071 0F44        M    ADDWF   ACC+B0, F            ; add lowest byte of b, save in b(B0)
0072 6A19        M    MOVFP   DPX+B1,WREG          ; get 2nd byte of a into w
0073 1145        M    ADDWFC  ACC+B1, F            ; add 2nd byte of b, save in b(B1)
0074 6A1A        M    MOVFP   DPX+B2,WREG          ; get 3rd byte of a into w
0075 1146        M    ADDWFC  ACC+B2, F            ; add 3rd byte of b, save in b(B2)
0076 6A1B        M    MOVFP   DPX+B3,WREG          ; get 4th byte of a into w
0077 1147        M    ADDWFC  ACC+B3, F            ; add 4th byte of b, save in b(B3)
                 M
                 M ;
                 M ;  Compute A1*D(n-1)
                 M ;
                 M    MOVFP16  Dn2_1,AARG          ; AARG = D(n-2) = multiplier
                 M
0078 7C28        M    MOVFP   Dn2_1+B0,AARG+B0     ; move A(B0) to B(B0)
0079 7D29        M    MOVFP   Dn2_1+B1,AARG+B1     ; move A(B1) to B(B1)
                 M
                 M    MOVFP16  A21,BARG            ; BARG = A2 = multiplicand
                 M
007A 7E36        M    MOVFP   A21+B0,BARG+B0       ; move A(B0) to B(B0)
007B 7F37        M    MOVFP   A21+B1,BARG+B1       ; move A(B1) to B(B1)
                 M
007C E0AF        M    call    DblMult              ; (ACCd,ACCc) = A1*D(n-1)
                 M ;
                 M ; Compute A1*D(n-1) + A2*D(n-2) + output of previous section
                 M ;       multiplications already done, so simply perform a 32 bit add
                 M ;       of previously obtained multiplication results
                 M ;
                 M   ADD32   DPX,ACC              ; ACC = A1*D(n-1) + A2*D(n-2) +
                 M                                ;              (output of 1st section)
007D 6A18        M   MOVFP   DPX+B0,WREG          ; get lowest byte of a into w
007E 0F44        M   ADDWF   ACC+B0, F            ; add lowest byte of b, save in b(B0)
007F 6A19        M   MOVFP   DPX+B1,WREG          ; get 2nd byte of a into w
0080 1145        M   ADDWFC  ACC+B1, F            ; add 2nd byte of b, save in b(B1)
0081 6A1A        M   MOVFP   DPX+B2,WREG          ; get 3rd byte of a into w
0082 1146        M   ADDWFC  ACC+B2, F            ; add 3rd byte of b, save in b(B2)
0083 6A1B        M   MOVFP   DPX+B3,WREG          ; get 4th byte of a into w
0084 1147        M   ADDWFC  ACC+B3, F            ; add 4th byte of b, save in b(B3)
                 M
                 M ;
                 M ;
                 M ; save the upper 16 bits  of D(n) from the 32 bit accumulator
                 M ; left shift the result by 1, to adjust the decimal point after
                 M ; a Q15*Q15 multiplication
                 M ;
0085 1A45        M   rlcf    ACC+B1,w
0086 1A46        M   rlcf    ACC+B2,w
0087 0126        M   movwf   Dn2
0088 1A47        M   rlcf    ACC+B3,w             ; decimal adjust ( mult by 2)
0089 0127        M   movwf   Dn2+B1
                 M ;
                 M ; Compute B2 * [D(n) + D(n-2)]
                 M ;
                 M   #if B0_EQUALS_B2
                 M
                 M   ADD16ACC Dn2_2,Dn2,AARG      ; AARG = Dn + D(n-2) = multiplier
                 M
008A 6A2A        M   movfp   Dn2_2+B0,WREG
008B 0E26        M   addwf   Dn2+B0,w
008C 011C        M   movwf   AARG+B0
008D 6A2B        M   movfp   Dn2_2+B1,WREG
008E 1027        M   addwfc  Dn2+B1,w
008F 011D        M   movwf   AARG+B1
                 M
                 M   MOVFP16 B20,BARG             ; BARG = A2 = multiplicand
                 M
```

```
0090 7E3A       M   MOVFP   B20+B0,BARG+B0          ; move A(B0) to B(B0)
0091 7F3B       M   MOVFP   B20+B1,BARG+B1          ; move A(B1) to B(B1)
                M
0092 E0AF       M   call    DblMult                 ; (ACCd,ACCc) = B2*[D(n)+D(n-2)]
                M   MOVPF32 DPX,ACC
                M
0093 5844       M   MOVPF   DPX+B0,ACC+B0           ; move A(B0) to B(B0)
0094 5945       M   MOVPF   DPX+B1,ACC+B1           ; move A(B1) to B(B1)
0095 5A46       M   MOVPF   DPX+B2,ACC+B2           ; move A(B2) to B(B2)
0096 5B47       M   MOVPF   DPX+B3,ACC+B3           ; move A(B3) to B(B3)
                M
                M
                M   #else
                M
                M   MOVFP16 B20,BARG
                M   MOVFP16 Dn2,AARG
                M   call    DblMult                 ; B0*D(n)
                M   MOVPF32 DPX,ACC
                M
                M   MOVFP16 Bx2,BARG
                M   MOVFP16 Dn2_2,AARG
                M   call    DblMult                 ; B2*D(n-2)
                M   ADD32   DPX,ACC
                M
                M   #endif
                M ;
                M ; Shift down D(n-1) to D(n-2) after D(n-2) usage is no longer required.
                M ; This way in the next iteration D(n-2) is equal to the present D(n-1)
                M ;
0097 7C28       M  movfp    Dn2_1,AARG+B0
0098 5C2A       M  movpf    AARG+B0,Dn2_2           ; Shift down D(n-1)
0099 7D29       M  movfp    Dn2_1+B1,AARG+B1
009A 5D2B       M  movpf    AARG+B1,Dn2_2+B1        ; AARG = D(n-1) = multiplier
                M
                M  MOVFP16  B21,BARG                ; BARG = B1 = multiplicand
                M
009B 7E3C       M  MOVFP   B21+B0,BARG+B0           ; move A(B0) to B(B0)
009C 7F3D       M  MOVFP   B21+B1,BARG+B1           ; move A(B1) to B(B1)
                M
                M
009D E0AF       M  call    DblMult                  ; (ACCd,ACCc) = B1*D(n-1)
                M ;
                M ; Compute Output Y = B1*D(n-1) + B2*D(n-2) + B0*D(n)
                M ;                  = B1*D(n-1) + B0*[D(n) + D(n-2)]
                M ; Since all multiplications are already done, simply perform a
                M ; 32 bit addition
                M ;
                M   ADD32   DPX,ACC                 ; ACC = B1*D(n-1) + B2*D(n-2) + B0*D(n)
                M
009E 6A18       M   MOVFP   DPX+B0,WREG             ; get lowest byte of a into w
009F 0F44       M   ADDWF   ACC+B0, F               ; add lowest byte of b, save in b(B0)
00A0 6A19       M   MOVFP   DPX+B1,WREG             ; get 2nd byte of a into w
00A1 1145       M   ADDWFC  ACC+B1, F               ; add 2nd byte of b, save in b(B1)
00A2 6A1A       M   MOVFP   DPX+B2,WREG             ; get 3rd byte of a into w
00A3 1146       M   ADDWFC  ACC+B2, F               ; add 3rd byte of b, save in b(B2)
00A4 6A1B       M   MOVFP   DPX+B3,WREG             ; get 4th byte of a into w
00A5 1147       M   ADDWFC  ACC+B3, F               ; add 4th byte of b, save in b(B3)
                M
                M ;
                M ; Shift down D(n) to D(n-1) so that in the next iteration, the new
                M ; D(n-1) is the present D(n)
                M ;
                M   MOV16   Dn2,Dn2_1               ; Shift down D(n) to D(n-1)
                M
00A6 6A26       M   MOVFP   Dn2+B0,WREG             ; get byte of a into w
00A7 0128       M   MOVWF   Dn2_1+B0                ; move to b(B0)
```

```
00A8 6A27        M   MOVFP   Dn2+B1,WREG          ; get byte of a into w
00A9 0129        M   MOVWF   Dn2_1+B1             ; move to b(B1)
                 M
                 M ;
                00269 ;
                00270 ; The filter output is now computed
                00271 ; Save the Upper 16 Bits of 32 bit Accumulator into Y after
                00272 ; adjusting the decimal point
                00273 ;
                00274
                00275   MOV16   ACC+BB2,Y
                   M
00AA 6A46          M   MOVFP   ACC+BB2+B0,WREG      ; get byte of a into w
00AB 0142          M   MOVWF   Y+B0                 ; move to b(B0)
00AC 6A47          M   MOVFP   ACC+BB2+B1,WREG      ; get byte of a into w
00AD 0143          M   MOVWF   Y+B1                 ; move to b(B1)
                   M
                00276 ;
00AE 0002       00277   return                       ; Output Y(n) computed
                00278 ;
                00279 ;*****************************************************************
                00280 ;  Set SIGNED/UNSIGNED Flag Before Including 17c42MPY.mac
                00281 ;
                00282   #include        <17c42MPY.mac>
                00178   LIST
                00283
                00284 ;*****************************************************************
                00285 ;  Low Pass Filter Co-efficients
                00286 ;
                00287 ;
                00288 ;                 ELLIPTIC     LOWPASS FILTER
                00289 ;
                00290 ;                 FILTER ORDER =    4
                00291 ;                 Sampling frequency =   2.000  KiloHertz
                00292 ;
                00293 ;                          BAND  1         BAND  2
                00294 ;
                00295 ;
                00296 ; LOWER BAND EDGE          .00000          .60000
                00297 ; UPPER BAND EDGE          .50000         1.00000
                00298 ; NOMINAL GAIN            1.00000          .00000
                00299 ; NOMINAL RIPPLE           .01000          .05000
                00300 ; MAXIMUM RIPPLE           .00906          .04601
                00301 ; RIPPLE IN dB             .07830       -26.74235
                00302 ;
                00303 ;  I    A(I,1)        A(I,2)        B(I,0)        B(I,1)        B(I,2)
                00304 ;
                00305 ;  1    -.133331       .167145       .285431       .462921       .285431
                00306 ;       .147827       .765900       .698273       .499908       .698273
                00307 ;
                00308
01C1            00309 _coeff_lpass              ; co-efficients for 1st Cascade section
01C1 1111       00310         data     4369             ; -A11
01C2 EA9B       00311         data     -5477            ; -A12
01C3 2489       00312         data     9353             ; B10
01C4 3B41       00313         data     15169            ; B11
01C5 2489       00314         data     9353             ; B12
                00315                           ; co-efficients for 2nd Cascade section
01C6 ED14       00316         data    -4844             ; -A21
01C7 9DF7       00317         data    -25097            ; -A22
01C8 5961       00318         data     22881            ; B20
01C9 3FFD       00319         data     16381            ; B21
01CA 5961       00320         data     22881            ; B22
                00321 ;
                00322 ;*****************************************************************
                00323 ;
```

```
00324 ;
00325 ;*********************************************************************
00326 ;  High Pass Filter Co-efficients
00327 ;
00328 ;
00329 ;                ELLIPTIC    HIGHPASS FILTER
00330 ;
00331 ;                FILTER ORDER =    4
00332 ;                Sampling frequency =   2.000  KiloHertz
00333 ;
00334 ;                       BAND  1        BAND  2
00335 ;
00336 ;
00337 ; LOWER BAND EDGE          .00000         .50000
00338 ; UPPER BAND EDGE          .40000        1.00000
00339 ; NOMINAL GAIN             .00000        1.00000
00340 ; NOMINAL RIPPLE          .04000         .02000
00341 ; MAXIMUM RIPPLE          .03368         .01686
00342 ; RIPPLE IN dB         -29.45335         .14526
00343 ;
00344 ;  I      A(I,1)         A(I,2)        B(I,0)        B(I,1)        B(I,2)
00345 ;
00346 ;  1     .276886        .195648       .253677       -.411407       .253677
00347 ;  2    -.094299        .780396       .678650       -.485840       .678650
00348 ;
00349 ;
01CB          00350 _coeff_hpass            ; co-efficients for 1st Cascade section
01CB DC8F     00351         data     -9073          ; -A11
01CC E6F5     00352         data     -6411          ; -A12
01CD 2079     00353         data     8313           ; B10
01CE CB57     00354         data     -13481         ; B11
01CF 2079     00355         data     8313           ; B12
              00356 ;                       ; co-efficients for 2nd Cascade section
01D0 0C12     00357         data     3090           ; -A21
01D1 9C1C     00358         data     -25572         ; -A22
01D2 56DE     00359         data     22238          ; B20
01D3 C1D0     00360         data     -15920         ; B21
01D4 56DE     00361         data     22238          ; B22
              00362 ;
              00363 ;*********************************************************************
              00364 ;
              00365 ;*********************************************************************
              00366 ;  Band Pass Filter Co-efficients
              00367 ;
              00368 ;
              00369 ;                ELLIPTIC     BANDPASS FILTER
              00370 ;
              00371 ;                FILTER ORDER =    4
              00372 ;                Sampling frequency =   2.000  KiloHertz
              00373 ;
              00374 ;                       BAND  1        BAND  2        BAND  3
              00375 ;
              00376 ;
              00377 ; LOWER BAND EDGE          .00000         .30000         .90000
              00378 ; UPPER BAND EDGE          .10000         .70000        1.00000
              00379 ; NOMINAL GAIN             .00000        1.00000         .00000
              00380 ; NOMINAL RIPPLE           .05000         .05000         .05000
              00381 ; MAXIMUM RIPPLE           .03644         .03867         .03641
              00382 ; RIPPLE IN dB         -28.76779         .32956      -28.77647
              00383 ;
              00384 ;
              00385 ;  I      A(I,1)         A(I,2)        B(I,0)        B(I,1)        B(I,2)
              00386 ;
              00387 ;  1    -.936676        .550568       .444000       -.865173       .444000
              00388 ;  2     .936707        .550568       .615540       1.199402       .615540
              00389 ;
```

```
                00390
01D5            00391 _coeff_bpass                    ; co-efficients for 1st Cascade section
01D5 3BF2       00392         data     30693/2          ; -A11
01D6 DCC4       00393         data     -18041/2         ; -A12
01D7 1C6A       00394         data     14549/2          ; B10
01D8 C8A1       00395         data     -28350/2         ; B11
01D9 1C6A       00396         data     14549/2          ; B12
                00397 ;                               ; co-efficients for 2nd Cascade section
01DA C40D       00398         data    -30694/2          ; -A21
01DB DCC4       00399         data    -18041/2          ; -A22
01DC 2765       00400         data     20170/2          ; B20
01DD 4CC3       00401         data     39302/2          ; B21
01DE 2765       00402         data     20170/2          ; B22
                00403 ;
                00404 ;*****************************************************************
                00405 ;
                00406 ;*****************************************************************
                00407 ;  Band Stop Filter Co-efficients
                00408 ;
                00409 ;
                00410 ;                          ELLIPTIC    BANDSTOP FILTER
                00411 ;
                00412 ;                  FILTER ORDER =    4
                00413 ;                  Sampling frequency =   2.000  KiloHertz
                00414 ;
                00415 ;                           BAND  1         BAND  2         BAND  3
                00416 ;
                00417 ;
                00418 ;LOWER BAND EDGE          .00000          .45000          .70000
                00419 ;UPPER BAND EDGE          .30000          .55000         1.00000
                00420 ;NOMINAL GAIN            1.00000          .00000         1.00000
                00421 ;NOMINAL RIPPLE           .05000          .05000          .05000
                00422 ;MAXIMUM RIPPLE           .03516          .03241          .03517
                00423 ;RIPPLE IN dB             .30015       -29.78523          .30027
                00424 ;
                00425 ;
                00426 ;  I      A(I,1)         A(I,2)         B(I,0)         B(I,1)         B(I,2)
                00427 ;
                00428 ;  1     .749420        .583282        .392685        .087936        .392685
                00429 ;  2    -.749390        .583282       1.210022       -.270935       1.210022
                00430 ;
01DF            00431 _coeff_bstop                    ; co-efficients for 1st Cascade section
01DF D00A       00432         data     -24557/2         ; -A11
01E0 DAAC       00433         data     -19113/2         ; -A12
01E1 1922       00434         data     12868/2          ; B10
01E2 05A0       00435         data     2881/2           ; B11
01E3 1922       00436         data     12868/2          ; B12
                00437                                 ; co-efficients for 2nd Cascade section
01E4 2FF6       00438         data    24556/2           ; -A21
01E5 DAAC       00439         data    -19113/2          ; -A22
01E6 4D71       00440         data    39650/2           ; B20
01E7 EEA9       00441         data    -8878/2           ; B21
01E8 4D71       00442         data    39650/2           ; B22
                00443 ;
                00444 ;*****************************************************************
                00445
                00446         END
```

```
MEMORY USAGE MAP ('X' = Used,  '-' = Unused)

0000 : XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX
0040 : XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX
0080 : XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX
00C0 : XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX
0100 : XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX
0140 : XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX
0180 : XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX
01C0 : XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX XXXXXXXXX------- ----------------

All other memory blocks unused.

Program Memory Words Used:   489


Errors   :     0
Warnings :     0 reported,     0 suppressed
Messages :     0 reported,     0 suppressed
```

**Note the following details of the code protection feature on PICmicro® MCUs.**

- The PICmicro family meets the specifications contained in the Microchip Data Sheet.
- Microchip believes that its family of PICmicro microcontrollers is one of the most secure products of its kind on the market today, when used in the intended manner and under normal conditions.
- There are dishonest and possibly illegal methods used to breach the code protection feature. All of these methods, to our knowledge, require using the PICmicro microcontroller in a manner outside the operating specifications contained in the data sheet. The person doing so may be engaged in theft of intellectual property.
- Microchip is willing to work with the customer who is concerned about the integrity of their code.
- Neither Microchip nor any other semiconductor manufacturer can guarantee the security of their code. Code protection does not mean that we are guaranteeing the product as "unbreakable".
- Code protection is constantly evolving. We at Microchip are committed to continuously improving the code protection features of our product.

If you have any further questions about this matter, please contact the local sales office nearest to you.



DNV Certification, Inc. USA — ANSI-RAB QMS ACCREDITED — DNV MSC The Netherlands Accredited by the RvA — DNV — ISO 9001 / QS-9000 REGISTERED FIRM

*Microchip received QS-9000 quality system certification for its worldwide headquarters, design and wafer fabrication facilities in Chandler and Tempe, Arizona in July 1999. The Company's quality system processes and procedures are QS-9000 compliant for its PICmicro® 8-bit MCUs, KEELOQ® code hopping devices, Serial EEPROMs and microperipheral products. In addition, Microchip's quality system for the design and manufacture of development systems is ISO 9001 certified.*